



Beyond the Blackwell order in dichotomies[☆]

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ABSTRACT

I establish a translation invariance property of the Blackwell order for dichotomies and show that the norm of the distance from the identity matrix may be interpreted as a measure of informativeness. The better experiment is closer to the fully revealing experiment; this measure extends the Blackwell order, is complete, and prior-independent.

1. Introduction

In a bedrock contribution (Blackwell, 1951, 1953), David Blackwell established the equivalence of two notions of ordinal rankings of experiments — those of informativeness, and of payoff-richness (as well as the related notion of sufficiency). Here I first ask whether the Blackwell order is preserved when both the better and the worse experiments are garbled using the same garbling, and then show that the matrix norm of the difference between a fully revealing experiment and the experiment being ranked is a convenient and appealing completion of the Blackwell order. An application illustrating this completion concludes. Throughout, I focus only on dichotomies: experiments with two states and two signal realizations.

Section 2 first asks: Given two Blackwell-ranked experiments, is the order preserved if signal realizations from both experiments are subjected to noise? More precisely, suppose both experiments undergo yet another stochastic transformation, say, M . If A Blackwell-dominates B , does experiment MA always Blackwell-dominate experiment MB ? Theorem 1 answers in the affirmative, highlighting a curious translation invariance property.

Equally important is the question of completing the (notoriously partial) Blackwell order. Theorem 2 shows that all dichotomous experiments are ranked by taking the infinity norm of the difference between any experiment and the fully revealing experiment. The interpretation is that more informative experiments are “closer” to the fully revealing experiment (represented by the identity matrix). This (prior-independent) measure completes Blackwell’s order within this

class of experiments. Two counterexamples follow each of Theorem 1 and Theorem 2, showing that neither result can be extended beyond two states or two signal realizations.

There is renewed interest in features of the Blackwell order (Wenhao, 2023; Ben-Shahar and Sulganik, 2024). Restricting attention to 2×2 dichotomies is common; the underlying state in interesting problems often is binary (the product, project, firm, or match, is truly good or bad) and thus the assumption of two states is common in this literature (Keppo et al., 2008; de Oliveira et al., 2021; Mu et al., 2021). Assuming binary signal realizations (studied also in Birnbaum (1961) “simple binary experiments”, Torgersen (1970) “double dichotomies”, and Blackwell and Girshik (1979) “binomial dichotomies”) reflects the fact that much of the relevant evidence (passing or failing a test or an audit, presence or absence of a pathogen or biomarker) in these settings is also binary. In addition, many economic decisions are binary (convict/acquit, purchase/not, approve/disapprove, vote yes/no, tests of simple hypotheses); with binary decisions, and multiple signal realizations, many of those signals would lead to one of the two decisions,¹ effectively acting as one signal realization.

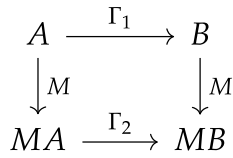
Notation

Throughout, the state space $\Omega = \{\omega_0, \omega_1\} = \{0, 1\}$ and the signal space $S = \{s_0, s_1\}$ are fixed. A Blackwell experiment is a 2×2 stochastic matrix $P = \{p_{ij}\}$ (i.e. $p_{ij} \geq 0$, and for each j , $p_{1j} + p_{2j} = 1$; the matrix is column-stochastic, with entries representing the probabilities

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¹ An insightful anonymous referee points out that with two states, two actions, and many signal realizations, the composition of an experiment with a strategy is itself a dichotomy.

Fig. 1. Translation invariance of \succeq_B .

of signal realizations in each state). Denote by $\mathbb{1}$ the identity matrix, interpreted as a fully revealing experiment. Experiment A Blackwell dominates experiment B , (written $A \succeq_B B$), if and only if an expected utility-maximizing decision maker (DM) prefers A to B , or if and only if there exists a stochastic matrix Γ (a *garbling*), with $\Gamma A = B$. Denote by $\text{tr}(A)$ the *trace* of a matrix A (i.e. the sum of the main diagonal entries).

2. Translation invariance and a cardinal measure of informativeness

Given two Blackwell-ranked experiments, is the ordering preserved if signal realizations from both experiments are subjected to noise? More precisely, suppose both experiments undergo yet another garbling M . If A Blackwell-dominates B , does experiment MA Blackwell-dominate experiment MB ?

The question of noise added to signal realizations is animated by the growing research program grappling with the impact of noise, errors, inattention, and other imperfections in communication and interpretation, on established results. There are at least two reasons why such a second-order garbling may occur. First, the DM may be inattentive, and not recognize some signal realizations, merge, or misinterpret them (Bloedel and Segal, 2021). Second, the DM may observe signal realizations with transmission noise (Hernandez and von Stengel, 2014; Blume et al., 2007).

Theorem 1 gives the translation invariance result.

Theorem 1 (Translation Invariance of \succeq_B). Let Γ_1 be a garbling matrix with $\text{tr}(\Gamma_1) \geq 1$,² and take a non-singular experiment A . Let $B = \Gamma_1 A$ (i.e. $A \succeq_B B$). For any non-singular column-stochastic matrix M , we have that:

- (i) MA Blackwell-dominates MB , and
- (ii) There exists a garbling matrix Γ_2 , with Γ_2 similar to Γ_1 , such that $\Gamma_2 MA = MB$.

In other words, the diagram in Fig. 1 commutes.

Theorem 1 has two takeaways. One is that the Blackwell order is *translation invariant* - the garbling M “shifts” any experiment by an amount “proportional” to the initial distance, because the resulting matrices are still ranked. The second takeaway is that Γ_1 and Γ_2 are *similar* matrices — in other words, they represent the same linear transformation, but in different bases. Thus, the features of the linear transformation that have to do with the characteristic polynomial (which does not depend on the choice of basis), such as the determinant, trace and eigenvalues, but also the rank and the normal forms, are preserved. The fact that the linear operator mapping A into B , and the linear operator mapping MA into MB , turn out to be the *same* linear operator is thought-provoking.

For a minimal counterexample (showing that the theorem does not extend beyond two signal realizations),³ let $|\mathcal{Q}| = 2$, and $|\mathcal{S}| = 3$ and suppose A is a fully revealing experiment, and Γ_1 with $p, q \in (\frac{1}{2}, 1]$ is

given below, so that $B (= \Gamma_1 A)$ is partially revealing, and take M as below. Then $MA = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$, a fully uninformative experiment, and

$$MB = \begin{pmatrix} p & 1 \\ 1-p & 0 \end{pmatrix}. \text{ Clearly, } A \succ_B B, \text{ yet } MA <_B MB. \quad (1)$$

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \Gamma_1 = \begin{pmatrix} p & 1-q \\ 0 & q \\ 1-p & 0 \end{pmatrix},$$

For a 3×3 counterexample (showing that the theorem does not extend beyond two states), consider (letting $B = \Gamma_1 A$):

$$A = \begin{pmatrix} 0.9 & 0.25 & 0.15 \\ 0.05 & 0.5 & 0.15 \\ 0.05 & 0.25 & 0.7 \end{pmatrix}, \Gamma_1 = \begin{pmatrix} 0.51 & 0 & 0 \\ 0.49 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad (2)$$

Here MA does not Blackwell-dominate MB (the required Γ_2 is not stochastic).

Going beyond Theorem 1, and restricting attention to a particular norm – the infinity norm, denoted by $\|\cdot\|_\infty$ – we obtain a completion of Blackwell’s order, and a cardinal informativeness result.

Theorem 2 (A Cardinal Measure of Informativeness). Let A and B be two experiments, and suppose that $\text{tr}(A) \geq 1$.⁴ Then $A \succeq_B B$ implies $\|\mathbb{1} - A\|_\infty \leq \|\mathbb{1} - B\|_\infty$.

Thus, the “closer” a matrix is to full revelation, the “better” it is. The norm is a continuous function, and thus, if $A \succeq_B B$ are Blackwell ranked experiments, this completion assigns “nearby” unranked experiments values that are “close” to the values for A and B . Its interpretation also has the intuitively attractive features that relate this order to Blackwell’s, and to mean preserving spreads; Fig. 2 illustrates.

Unfortunately, Theorem 2 also does not extend beyond dichotomies. For a minimal counterexample with two states and three signal realizations, consider

$$A = \begin{pmatrix} 0.4870 & 0.5984 \\ 0.4386 & 0.2385 \\ 0.0744 & 0.1631 \end{pmatrix}, \Gamma = \begin{pmatrix} 0.2328 & 0.3042 & 0.1225 \\ 0.0644 & 0.2672 & 0.3710 \\ 0.7028 & 0.4286 & 0.5065 \end{pmatrix}, \quad (3)$$

Using $E = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$ in place of the identity for the norm computations we obtain: $\|E - A\|_\infty - \|E - B\|_\infty = 0.0268$. For an example with three states, let

$$A = \begin{pmatrix} 0.55 & 0 & 0 \\ 0.45 & 0.55 & 0.45 \\ 0 & 0.45 & 0.55 \end{pmatrix}, \Gamma = \begin{pmatrix} 0.5 & 1 & 0 \\ 0.5 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad (4)$$

where we let $B = \Gamma A$. In this case, $\|\mathbb{1} - A\|_\infty - \|\mathbb{1} - B\|_\infty = 0.075$.

² The $\text{tr}(\Gamma_1) \geq 1$ condition is without loss: if $\text{tr}(\Gamma_1) < 1$, there always exist a $\tilde{\Gamma}_1$ with $\text{tr}(\tilde{\Gamma}_1) \geq 1$, and A', B' Blackwell-equivalent to A, B , such that Theorem 1 holds. In economic terms, the condition on the trace of the garbling (or of an experiment) says that on average, the garbling preserves the “label” of the signal.

³ A version of this counterexample was suggested by Alex Frankel.

⁴ The condition $\text{tr}(A) \geq 1$ is without loss, because if $\text{tr}(A) < 1$, there exists a Blackwell-equivalent (and thus, generating the same Bayes-plausible distribution of posteriors) $A' (= PA)$ with $\text{tr}(A') \geq 1$. Alternatively, as signal labels have no content, in a dichotomy one can always relabel signals so that the trace condition holds.

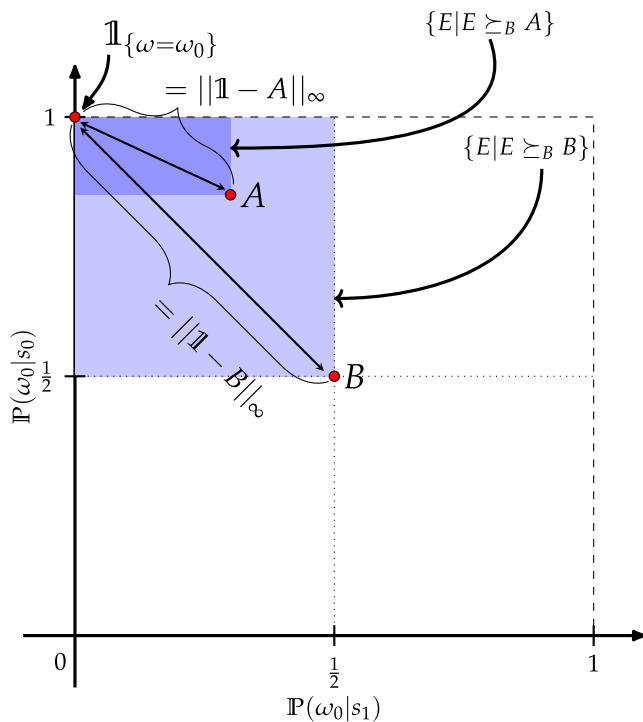


Fig. 2. $A \succeq_B B \implies A \succeq_{\|\cdot\|_\infty} B$: Blackwell informativeness and norm differences

The states are ω_0 and ω_1 , and signal realizations are s_0 and s_1 . The prior of $\omega = \omega_0$ is $\frac{1}{2}$, the true state is ω_0 , and A and B are (with abuse of nomenclature) two pairs of posterior beliefs resulting from the eponymous experiments. The possible posterior beliefs after a signal realization are on the axes; in light blue is the set of experiments and posterior belief distributions that are Blackwell better than B (and a mean-preserving spread of posteriors), while in dark blue is the corresponding set for A . E is a generic experiment (and associated posterior belief distribution). (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

An application

Suppose a von Neumann–Morgenstern DM faces a choice between experiments $A_1 = \begin{pmatrix} 0.7 & 0.4 \\ 0.3 & 0.6 \end{pmatrix}$, $A_2 = \begin{pmatrix} 0.75 & 0.25 \\ 0.25 & 0.75 \end{pmatrix}$, and a third experiment, $B = \begin{pmatrix} 0.85 & 0.49 \\ 0.15 & 0.51 \end{pmatrix}$, which is more informative than the other two in one state, and nearly uninformative in the other. A_2 Blackwell-dominates A_1 , yet B is not ranked vis-à-vis either A_1 or A_2 . In terms of norm distances, we have:

$$\|\mathbb{1} - A_1\|_\infty = 0.7 > \|\mathbb{1} - B\|_\infty = 0.64 > \|\mathbb{1} - A_2\|_\infty = 0.5 \quad (5)$$

How should a DM who cares about action in *both* states choose? From a (non-Blackwell-ranked) menu $\mathcal{M}_1 = \{A1, B\}$ the infinity norm difference order says that a DM should chose B (B is closer to full revelation as evidenced by a *smaller* distance to full revelation than A_1), and from a menu $\mathcal{M}_2 = \{B, A2\}$ they should choose A_2 .

Notably, completing the Blackwell order using norms in dichotomies is (unlike other completions of the order) prior-independent, stated without reference to a decision problem (and thus not tied to a utility specification), simple and easy to compute, and easily interpretable in terms of mean-preserving spreads.

Appendix. Proofs

Proof of Theorem 1.

$\Gamma_1 A = B$ by assumption; if a Γ_2 with the stated properties, exists, we would have $\Gamma_2 M A = M B$. But then

$$\Gamma_2 MA = MB \iff \Gamma_2 MA = M\Gamma_1 A \quad (6)$$

$$\Rightarrow \Gamma_2 M = M \Gamma_1 \quad (7)$$

$$\Rightarrow \Gamma_2 = M \Gamma_1 M^{-1} \quad (8)$$

Substituting the resulting F_2 verifies what was needed to show; the last equation confirms that the fact that F_1 and F_2 are similar matrices and gives an explicit formula for F_2 . It remains to show that F_2 is a garbling (i.e a stochastic matrix). Computing explicitly we obtain

$$\begin{aligned}
M \Gamma_1 M^{-1} &= \underbrace{\begin{pmatrix} m_1 & 1-m_2 \\ 1-m_1 & m_2 \end{pmatrix}}_M \underbrace{\begin{pmatrix} \gamma_1 & 1-\gamma_2 \\ 1-\gamma_1 & \gamma_2 \end{pmatrix}}_{\Gamma_1} \underbrace{\frac{1}{|M|} \begin{pmatrix} m_2 & m_2-1 \\ m_1-1 & m_1 \end{pmatrix}}_{M^{-1}} = \\
\end{aligned} \tag{9}$$

$$= \begin{pmatrix} \gamma_2 + m_1 - m_2 + \gamma_1 m_2 - \gamma_2 m_1 & m_1 - \gamma_1 - m_2 + \gamma_1 m_2 - \gamma_2 m_1 + 1 \\ m_2 - m_1 - \gamma_2 - \gamma_1 m_2 + \gamma_2 m_1 + 1 & \gamma_1 - m_1 + m_2 - \gamma_1 m_2 + \gamma_2 m_1 \end{pmatrix} \quad (10)$$

with $|M| = m_1 m_2 - (1 - m_2)(1 - m_1) = m_1 + m_2 - 1$. The columns sum to unity, so to show that Γ_2 is stochastic it suffices to show that $\gamma_2 + m_1 - m_2 + \gamma_1 m_2 - \gamma_2 m_1$ and $\gamma_1 - m_1 + m_2 - \gamma_1 m_2 + \gamma_2 m_1$ terms are both in $[0, 1]$. Solving

$$\max_{m_1, m_2, \gamma_1, \gamma_2} \gamma_2 + m_1 - m_2 + \gamma_1 m_2 - \gamma_2 m_1 \quad (11)$$

$$s.t. \quad \gamma_1 + \gamma_2 \geq 1 \quad (12)$$

$$0 \leq m_1 \leq 1 \quad (13)$$

$$0 \leq m_7 \leq 1 \quad (14)$$

$$0 \leq \gamma_l \leq 1 \quad (15)$$

$$0 \leq \gamma_2 \leq 1 \quad (16)$$

yields many solutions (e.g. $\gamma_2 = m_1 = 1, m_2 = 0$, and any γ_1), all with the objective function value at 1. The corresponding minimization problem (minimizing, instead of maximizing, Eq. (11), subject to the same constraints) also yields many solutions (e.g. $m_1 = 0, m_2 = 1$ and any (γ_1, γ_2) with $\gamma_1 + \gamma_2 = 1$), with the objective value at 0. The corresponding optimization problems for the $\gamma_1 - m_1 + m_2 - \gamma_1 m_2 + \gamma_2 m_1$ term are analogous, have the same conclusion, and are therefore omitted. Thus, both terms are between 0 and 1.⁵

To see that the $\gamma_1 + \gamma_2 \geq 1$ condition is without loss of generality, fix an arbitrary B and consider the set $\mathcal{A} = \{A | A \succeq_B B\}$. Let \mathcal{A}' be the set $\mathcal{A}' = \{A' | \Gamma_1 A' = B, \text{tr}(\Gamma_1) \geq 1\}$ and \mathcal{A}'' be the set $\mathcal{A}'' = \{A'' | \Gamma_1 A'' = B, \text{tr}(\Gamma_1) < 1\}$. Note that \mathcal{A}' and \mathcal{A}'' form a partition of \mathcal{A} : they are mutually exclusive (as either the trace of the garbling is above unity, or it is not), and their union is \mathcal{A} . Let $\Gamma_1(A)$, $A \in \mathcal{A}$, be a function that maps A into the corresponding garbling (that garbles A into the B we fixed earlier). For all $A'' \in \mathcal{A}''$ let $\tilde{\Gamma}_1(A'') = P\Gamma_1(A'')$, where $P = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ is an (invertible) permutation matrix; this class of garblings $\tilde{\Gamma}_1$ satisfy the condition $\text{tr}(\tilde{\Gamma}_1) \geq 1$.⁶ Then $\tilde{\Gamma}_1(A'')A'' = B'$ with $B' \sim_B B$ because $\tilde{\Gamma}_1(A'')A'' = P\Gamma_1(A'')A'' = PB \equiv B'$. Clearly, $B \sim_B B'$ since $PB = B'$ and $PB' = B$.⁷ This shows that for any element in \mathcal{A}'' we can transform the associated Γ_1 in a Blackwell-equivalent way to satisfy the trace condition; the set \mathcal{A}' satisfied it by definition. Thus, because \mathcal{A}' and

⁵ Setting either $m_1 = 1$ and $m_2 = 0$ or $m_1 = 0$ and $m_2 = 1$ would violate the assumption that M is invertible; these solutions provide suprema and infima on the terms of \mathcal{I}_2 . If m_1 and m_2 are such that $|M| = m_1 + m_2 - 1 > 1$, the solutions to the optimizations change somewhat, with unique values for γ_1 and γ_2 , without changing the conclusion that the terms of \mathcal{I}_2 are in $[0, 1]$.

⁶ Since Γ_1 is a 2×2 column-stochastic matrix (and thus, the sum of all the entries is always equal to two), if $\text{tr}(\Gamma_1) < 1$, the *anti*-diagonal elements must sum to greater than one.

⁷ Experiments B and B' are equivalent iff one is a multiplication by a permutation matrix of the other (Marschak, 1971).

\mathcal{A}'' are a partition of \mathcal{A} , we are done: for any B and all A such that $A \succeq_B B$, there exists (modulo a Blackwell-equivalent transformation of B) a garbling Γ_1 with $\text{tr}(\Gamma_1) \geq 1$ such that $B = \Gamma_1 A$. \square

Proof of Theorem 2. Let $A = \begin{pmatrix} a_1 & 1-a_2 \\ 1-a_1 & a_2 \end{pmatrix}$. Because A Blackwell-dominates B by supposition, there exists some

$\Gamma = \begin{pmatrix} \gamma_1 & 1-\gamma_2 \\ 1-\gamma_1 & \gamma_2 \end{pmatrix}$ such that $B = \Gamma A$. Computing directly, $\|\mathbb{1} - A\|_\infty = 2 - a_1 - a_2$, therefore

$$\|\mathbb{1} - \Gamma A\|_\infty - \|\mathbb{1} - A\|_\infty = (2 - \gamma_1 - \gamma_2)(a_1 - a_2 - 1) \quad (17)$$

The term $2 - \gamma_1 - \gamma_2$ is always nonnegative (since Γ is column-stochastic), and the term $a_1 - a_2 - 1$ is nonnegative because of the supposition that $\text{tr}(A) = a_1 + a_2 \geq 1$. Thus,

$$\|\mathbb{1} - B\| - \|\mathbb{1} - A\| = \|\mathbb{1} - \Gamma A\| - \|\mathbb{1} - A\| \geq 0 \quad (18)$$

which completes the proof. \square

Data availability

No data was used for the research described in the article.

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